

## Collect parts and tools from the lists below:

Materials	Quantity
Screw, 8-32 x 1/4" Long	4
Screw, 8-32 x 1/2" Long	4
Screw, 8-32 x 3/8" Long	14
Motor Screw, Long [1/2"]	4
Nut, 8-32 Keps	18
Shaft, 3" long	3
Shaft, 2" long	2
Shaft Collar	6
Shaft Spacer Thin (4.6mm)	4
Shaft Spacer Thick (8mm)†	2
Bearing Flat	3
Standoff, 2" Long	2
Gear, 60 tooth	1
Gear, 36 tooth	2
Base Plate, 30x15 hole*	4
Slotted Angle, 30 hole*	2
Bar, 25 hole	1
Small Low Friction VEX Wheel	2
VEX PIC Microcontroller*	1
RF Receiver, 75MHz	1
VEX Motor	2
VEX Servo*	1
Optical Shaft Encoder*	1
Ultrasonic Rangefinder*	1
Potentiometer*	1
Bumper Switch*	1
Limit Switch*	1
Analog Accelerometer*	1
Light Sensor*	1
Line Tracker*	1
LED Indicator*	1

Tools	Quantity
Allen Wrench 3/32"	1
Allen Wrench 5/64"	1
Open End Wrench 1/4"	1
Hacksaw*	1

<sup>\*</sup> Not included in Protobot Robot Kit

<sup>†</sup> The Protobot Robot Kit contains too few



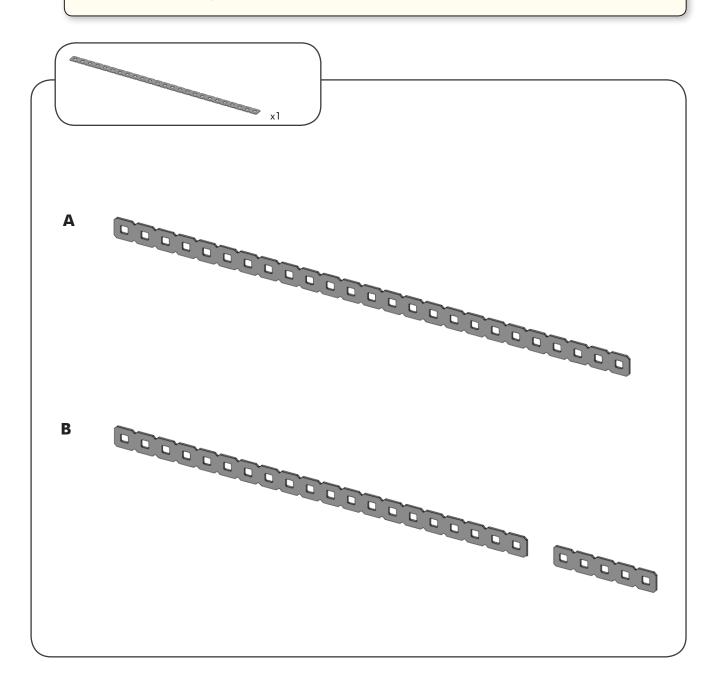
#### 2 Modifications



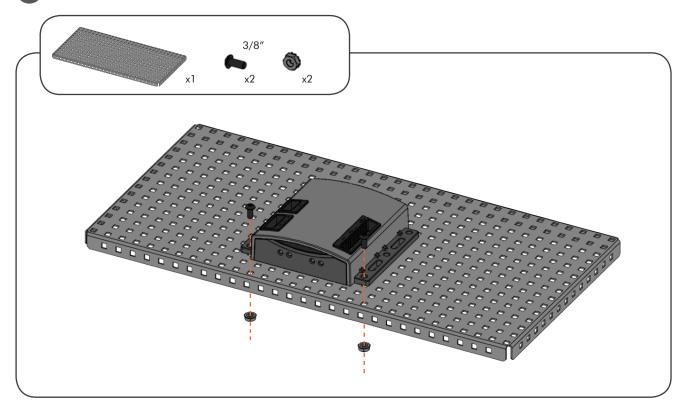
#### **CAUTION - Cutting VEX Metal**

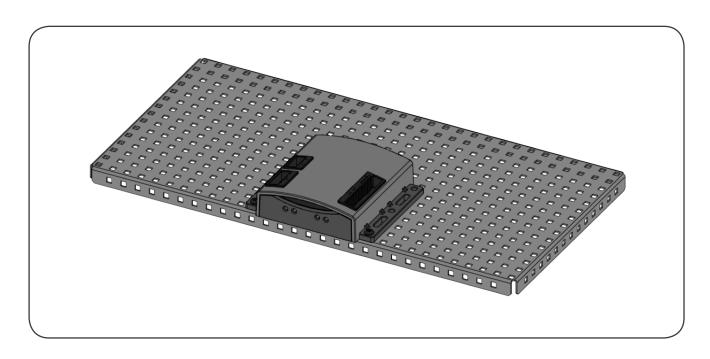
The following step involves permanent alterations to the materials in the VEX Kit. Make sure you have permission before continuing.

ALL APPLICABLE SAFETY PROCEDURES MUST BE OBSERVED WHILE PERFORMING THIS STEP. IF YOU ARE UNSURE ABOUT HOW TO USE THE TOOLS OR PERFORM THIS PROCEDURE SAFELY, DO NOT ATTEMPT THIS STEP ALONE. SEEK QUALIFIED ASSISTANCE BEFORE PROCEEDING.



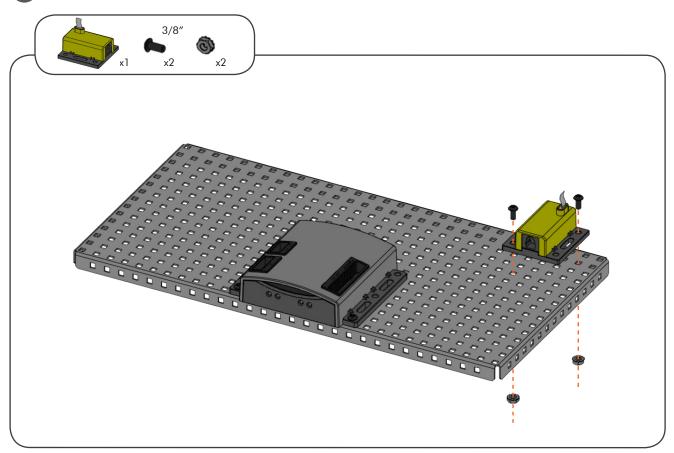
3 Attaching the VEX PIC Microcontroller

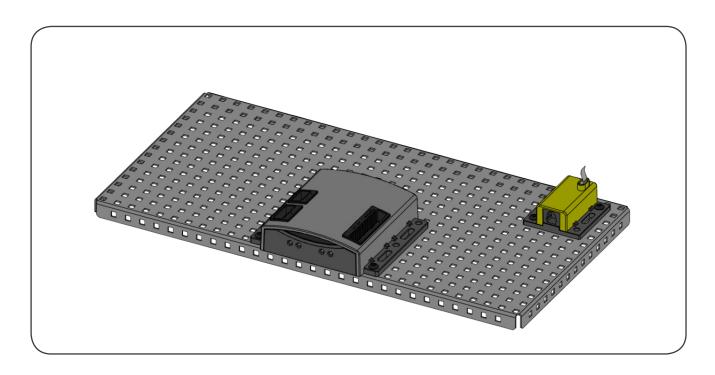




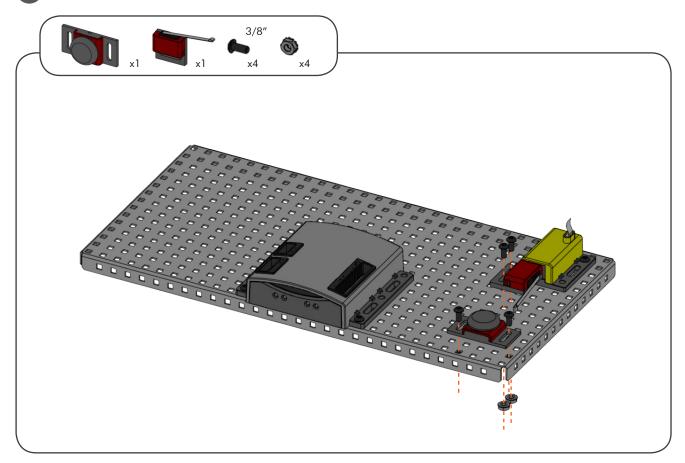
## PIC TESTBED BUILDING INSTRUCTIONS

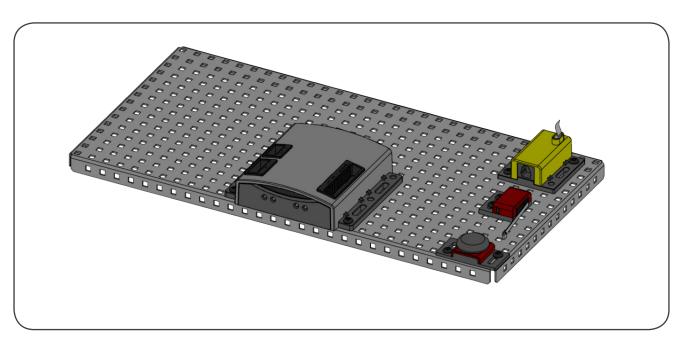
# Attaching the RF Receiver



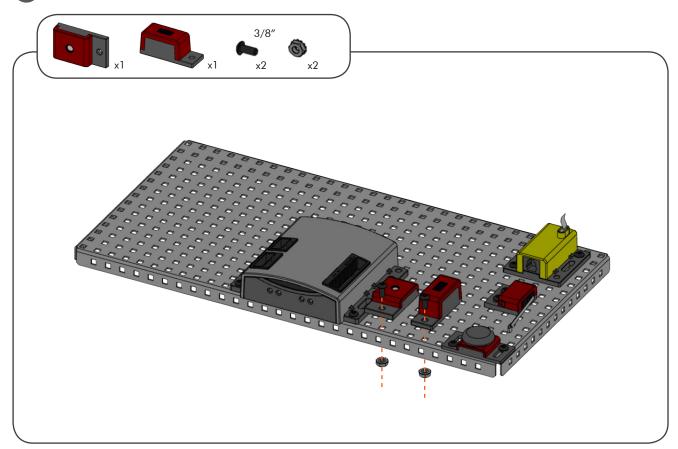


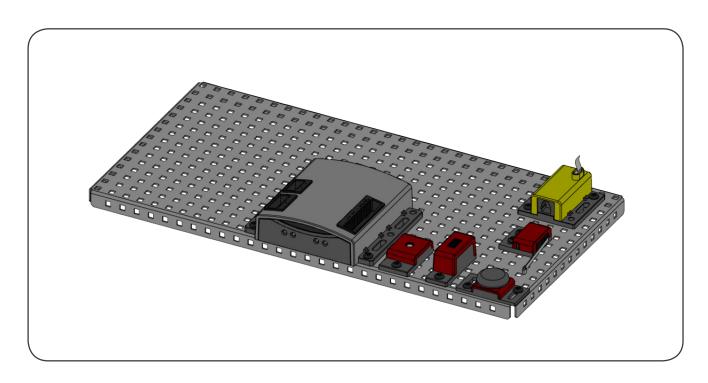
5 Attaching the Limit Switch and Bumper Switch



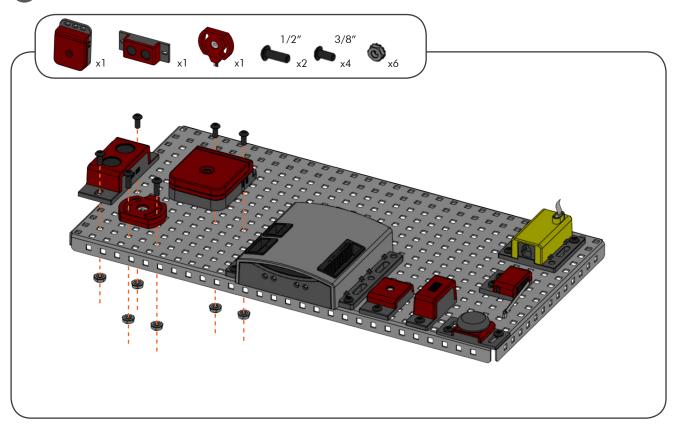


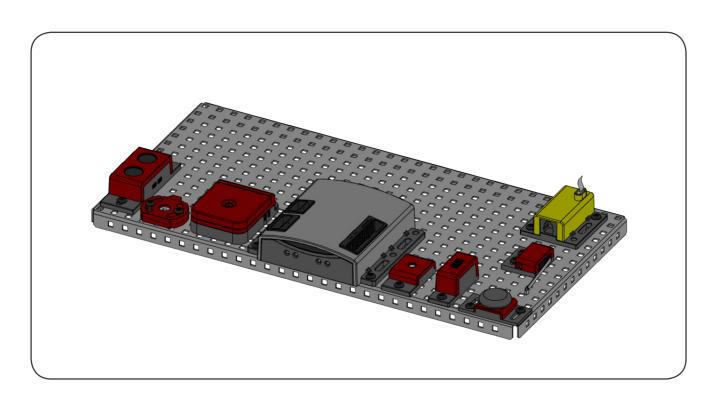
6 Attaching the Line Tracker and Light Sensor





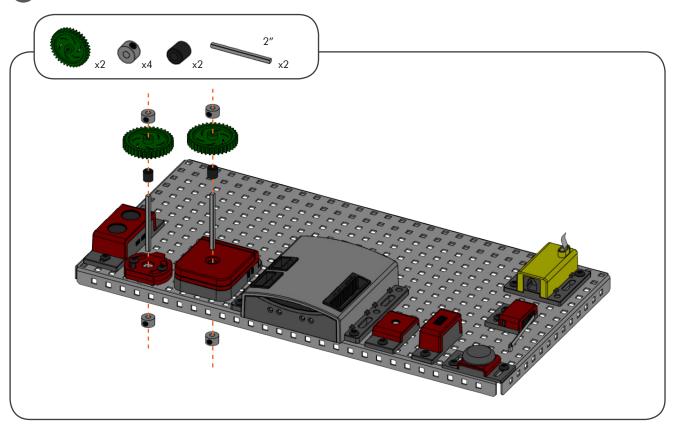
7 Attaching the Optical Shaft Encoder, Ultrasonic Rangefinder and Potentiometer

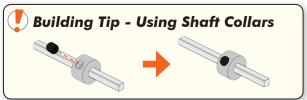


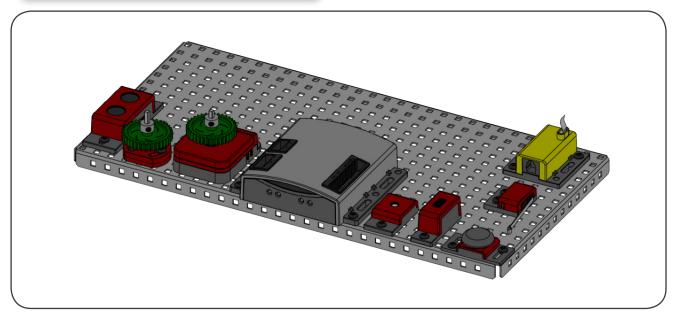


## PIC TESTBED BUILDING INSTRUCTIONS

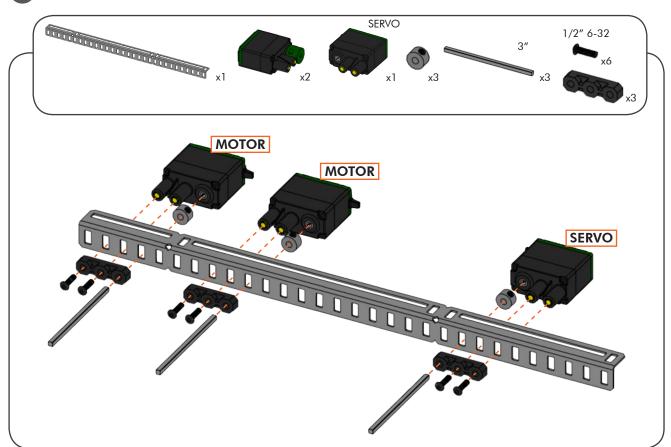
Attaching the Optical Shaft Encoder and Potentiometer (continued)

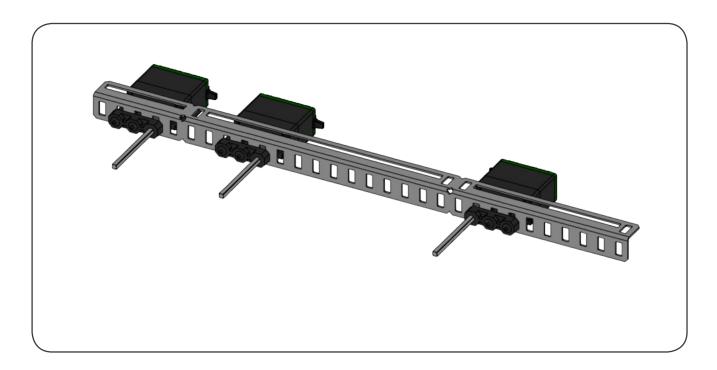






# 8 Motor Mount Construction

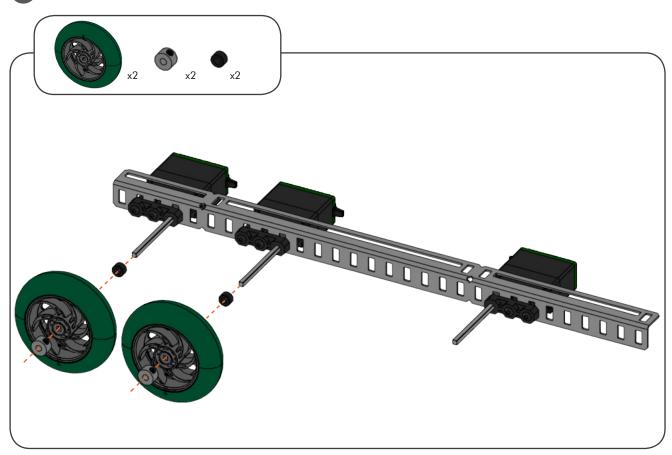


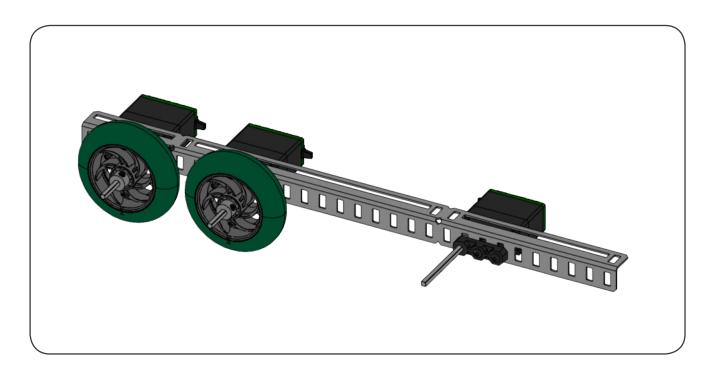


**ROBOTC** 

## PIC TESTBED BUILDING INSTRUCTIONS

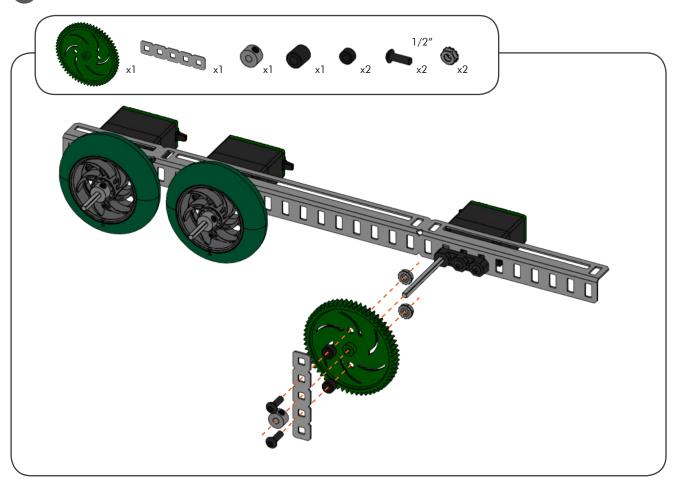
Motor Mount Construction (continued)

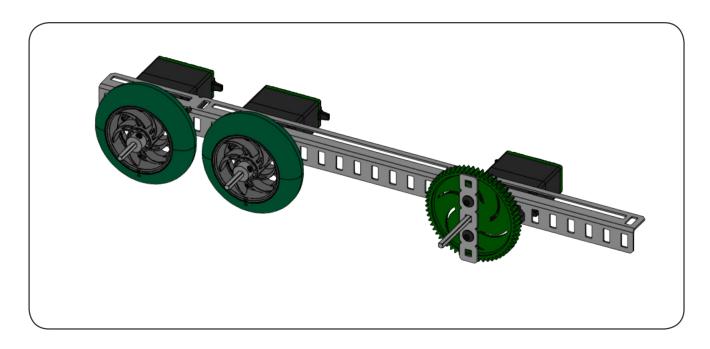




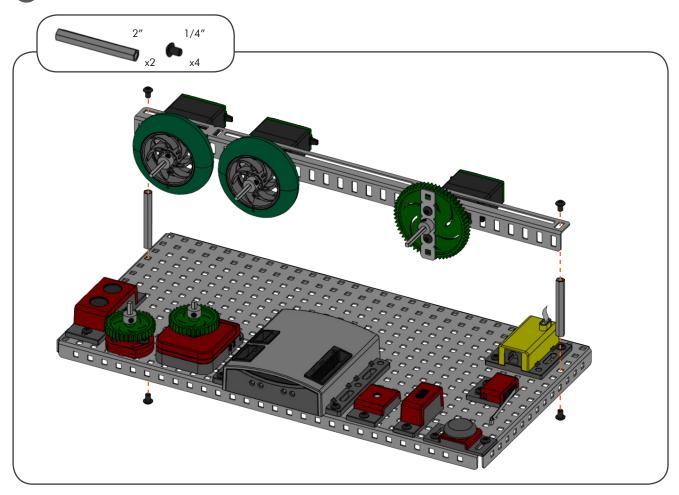
# PIC TESTBED BUILDING INSTRUCTIONS

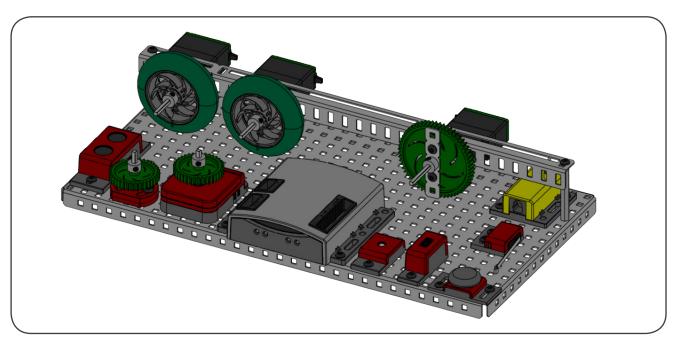
8 Motor Mount Construction (continued)





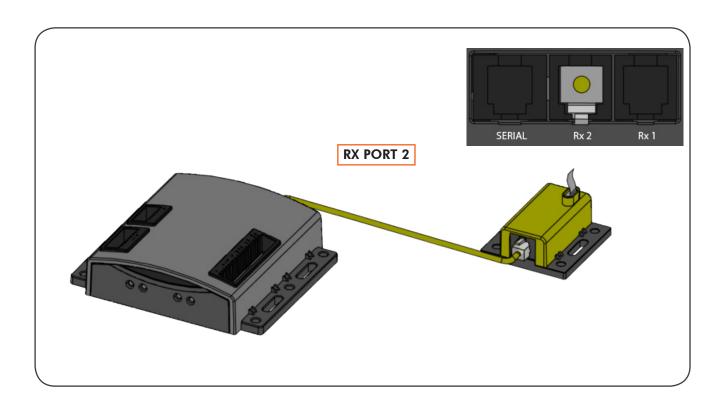
# **Attaching the Motor Mount**



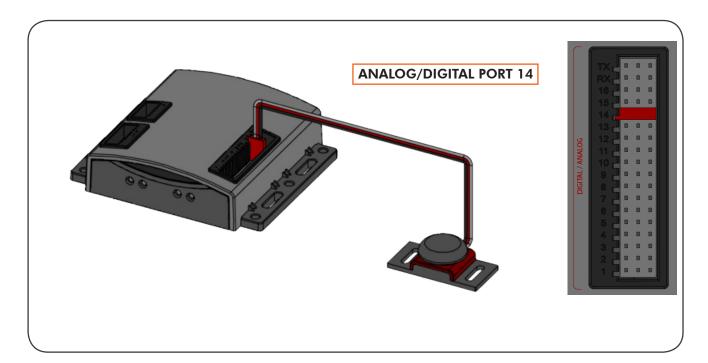


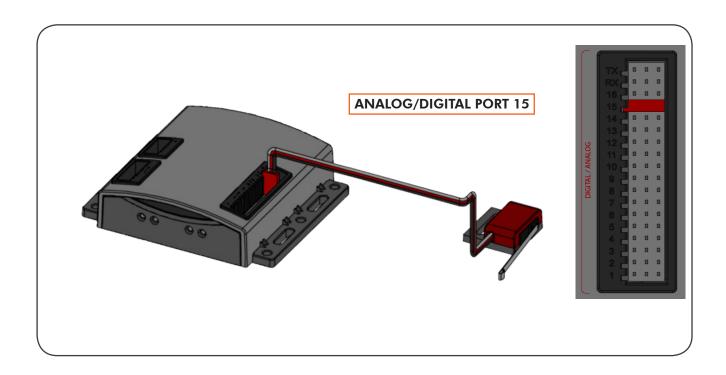
10 Attaching the LED Indicator and Wiring the RF Receiver



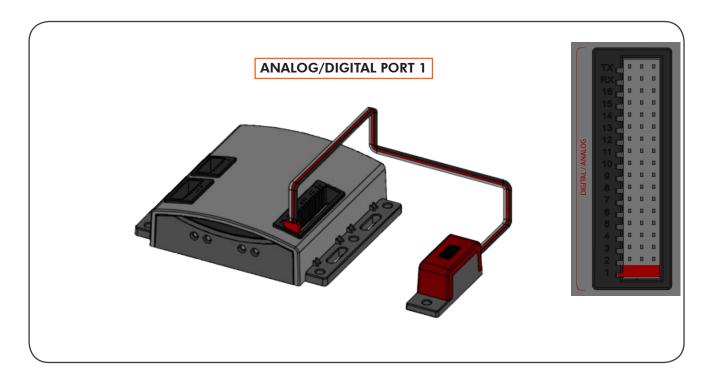


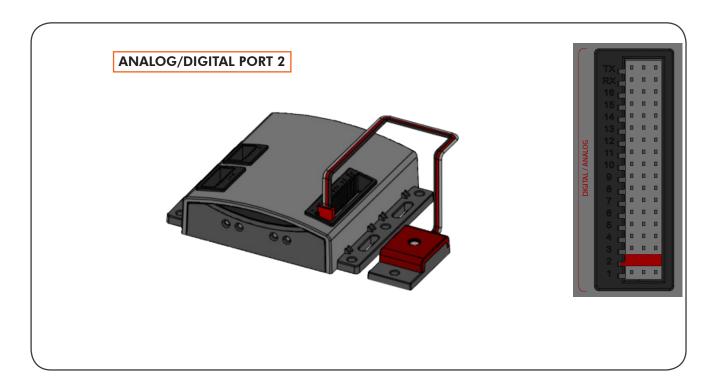
Wiring the Bumper Switch and Limit Switch



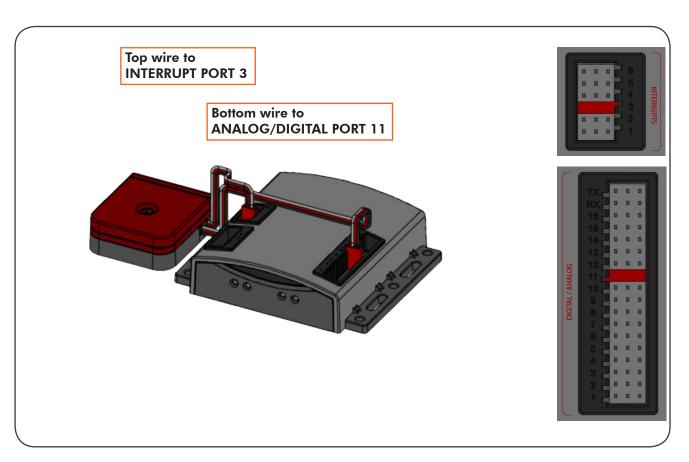


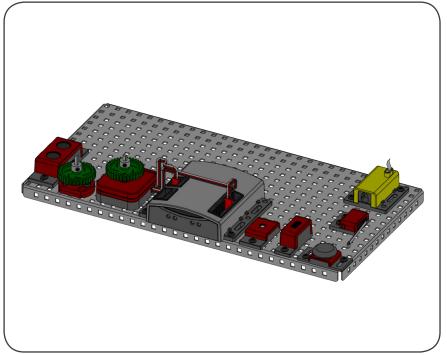
12 Wiring the Line Tracker and Light Sensor





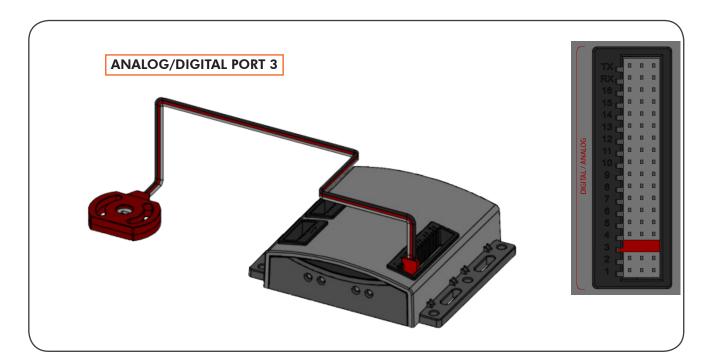
# 16 Wiring the Encoders

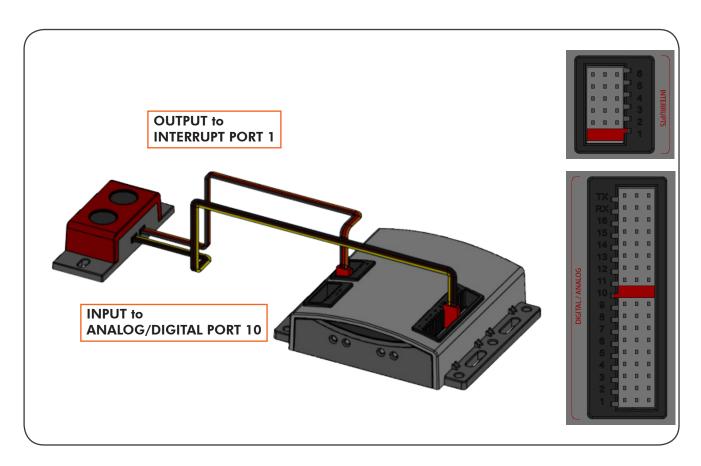




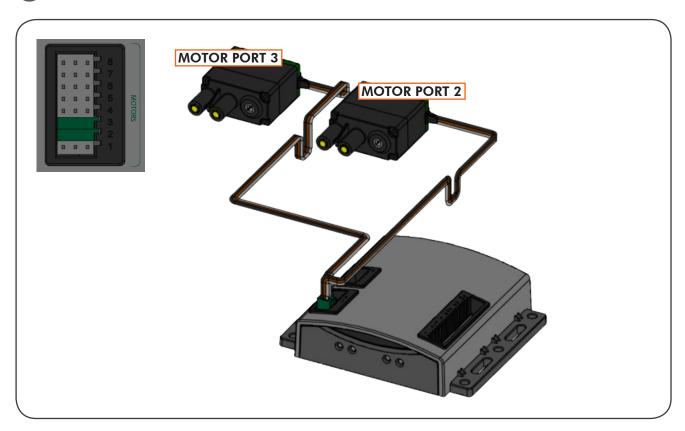


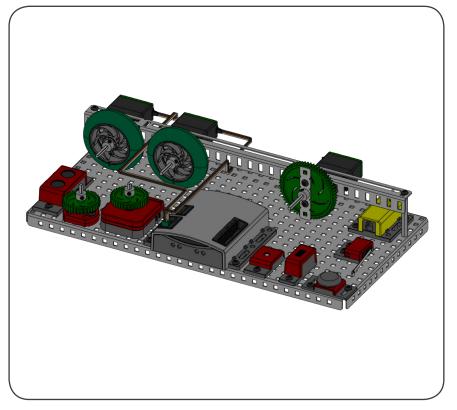
13 Wiring the Potentiometer and Ultrasonic Rangefinder

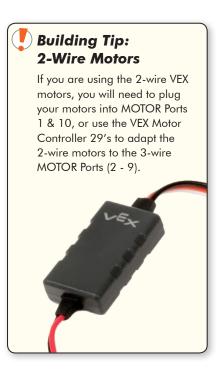




# 19 Wiring the Motors







# 20 Wiring the Servo

